## Use of hand-held NIR devices to predict the grass proportion in fresh grass-alfalfa mixtures: Improving sustainability in dairy systems



Rink Tacoma-Fogal
Cornell University
Co-authors: Debbie J.R. Cherney, May Boggess, Matt Digman \&

## Introduction

- Over $85 \%$ of alfalfa sown in New York state is done in combination with a perennial grass $\rightarrow$ soils have suboptimal drainage quality.
- Cows can produce more milk with mixtures $\rightarrow$ because grass tends to have much higher NDFD than alfalfa
- Knowing the grass:alfalfa proportions provides insight into:
- Estimating mixed stand forage quality (NDF)
- Helps the farmer decide when to reseed
- Information is used for nutrient management reporting.



## Motivation

- Hand-held NIR technology allows for dairy feed analysis results in real-time.
- Sample analysis is non-destructive and is designed to be used out in the field.
- A robust, well calibrated model developed for the NeoSpectra handheld device will provide farmers with the tools to accurately estimate alfalfa and grass \%'s in their forage crops.



## Objectives

1. Evaluate scanning technique and develop protocol for the using the hand-held NIR device for fresh grass:alfalfa mixtures.
2. Develop calibration equations (stationary and sliding) for the Neo Spectra Scanner to estimate grass \% in grass:alfalfa fresh mixtures.

## Methodology

## Sample collection and Scanning:

- Collected pure, fresh alfalfa and grass samples over a range of maturities and locations
- Fresh samples were chopped
- Alfalfa and grass were combined in known proportions.
- Samples were scanned four times using both stationary and sliding scans
- A portion of the samples was used for:

1) calibration development
2) the remaining used for model validation.


## Methodology

## Data analysis:

1. Averaged the 4 repeated scans for each sample with some outlier removal
2. For both stationary and sliding scans, a portion of the samples will be used:

- Calibration equation development ( $75 \%$ )
- The remaining used for external validation (25\%)

3. Preprocessing: mean centering, Savitzky-Golay smoothing, first and second derivative.

- Standard set of preprocessing methods to make better calibration equation


## Methodology

## Data analysis:

4. Fit partial least squares (PLS) model on the $75 \%$ calibration data:

- Reflectance's from 257 wavelengths is too many $\rightarrow$ PLS selects Latent Variables (LVs) that worked well for predicting grass \%
- How many LVs to select?
- Depends on how well they predict grass\% on unseen data (80:20 dataset split again $\rightarrow 5$-fold cross validation)

5. Applied the calibration equation to new data

- Applied the equation to the $25 \%$ external validation dataset and look at residuals to see how well it works on new data.

6. We used Matlab PLS Toolbox software program from Eigenvector

## Results

- Variability between stationary scans was greater than that of sliding scans

0\% Grass
Sample 1: $0.0 \%$ alfalfa



100\% Grass
Sample 116: $100.0 \%$ alfalfa

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## Results

- The variability was greater for the stationary scanning technique compared to the sliding method.




## Results

- High grass: above zero
- Low grass: below zero




## Results

|  | Calibration |  | Cross Validation |  | Prediction |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | R-squared | RMSE | R- squared |  | RMSE | R-squared |
| RMSE |  |  |  |  |  |  |
| Reflectance |  |  |  |  |  |  |
| Stationary |  |  |  |  |  |  |
| MC | $71.8 \%$ | 18.30 | $63.3 \%$ | 21.03 | $65.3 \%$ | 19.74 |
| SG | $71.8 \%$ | 18.33 | $63.3 \%$ | 21.03 | $65.3 \%$ | 19.75 |
| D1 | $77.0 \%$ | 16.53 | $66.1 \%$ | 20.30 | $70.2 \%$ | 18.33 |
| Sliding |  |  |  |  |  |  |
| MC | $84.9 \%$ | 13.40 | $80.4 \%$ | 15.30 | $77.9 \%$ | 15.59 |
| SG | $84.8 \%$ | 13.42 | $80.4 \%$ | 15.31 | $77.9 \%$ | 15.59 |
| D1 | $85.3 \%$ | 13.22 | $79.0 \%$ | 15.88 | $77.5 \%$ | 15.73 |
| Absorbance |  |  |  |  |  |  |
| Stationary |  |  |  |  |  |  |
| MC | $73.8 \%$ | 17.66 | $65.3 \%$ | 20.45 | $68.8 \%$ | 18.62 |
| SG | $73.7 \%$ | 17.70 | $65.2 \%$ | 20.48 | $68.6 \%$ | 18.67 |
| D1 | $77.7 \%$ | 16.29 | $66.2 \%$ | 20.28 | $71.2 \%$ | 17.82 |
| Sliding |  |  |  |  |  |  |
| MC | $88.3 \%$ | 11.76 | $84.0 \%$ | 13.79 | $83.4 \%$ | 13.58 |
| SG | $88.3 \%$ | 11.80 | $84.0 \%$ | 13.83 | $83.3 \%$ | 13.62 |
| D1 | $87.3 \%$ | 12.29 | $80.3 \%$ | 15.35 | $83.2 \%$ | 13.58 |

## Results

- Results from PLS regression on calibration and external validation dataset
- Correlation between the observed and the predicted is:
- 93\% for calibration dataset and $91 \%$ for external validation dataset

Sliding on calibration dataset


Sliding on external validation dataset
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## Conclusions

- Sliding scanning technique yields better predictions - may be due to the scanning capturing more of the variability that exists in the sample.
- Absorbance gave a better result for grass predictions in this study
- Mean-centering is just as good as other preprocessing methods
- PLS on NIR spectra can give a prediction on unseen data with a correlation of over $85 \%$ but there's room for improvement
- Improvements from this preliminary work:
- Further investigation on identifying outliers
- Evaluate impact of grass and alfalfa varieties


## What do these results mean for the farming community?

- Its feasible to use NIR on fresh forage samples, although further research is needed to improve accuracy.
- This research could improve the ability for grass-alfalfa producers to optimize field management and reduce variability in dairy rations, resulting in more environmentally and economically sustainable farming systems.




## Thankyou



## SARE Northeast <br> Sustainable Agriculture <br> Research and Education

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