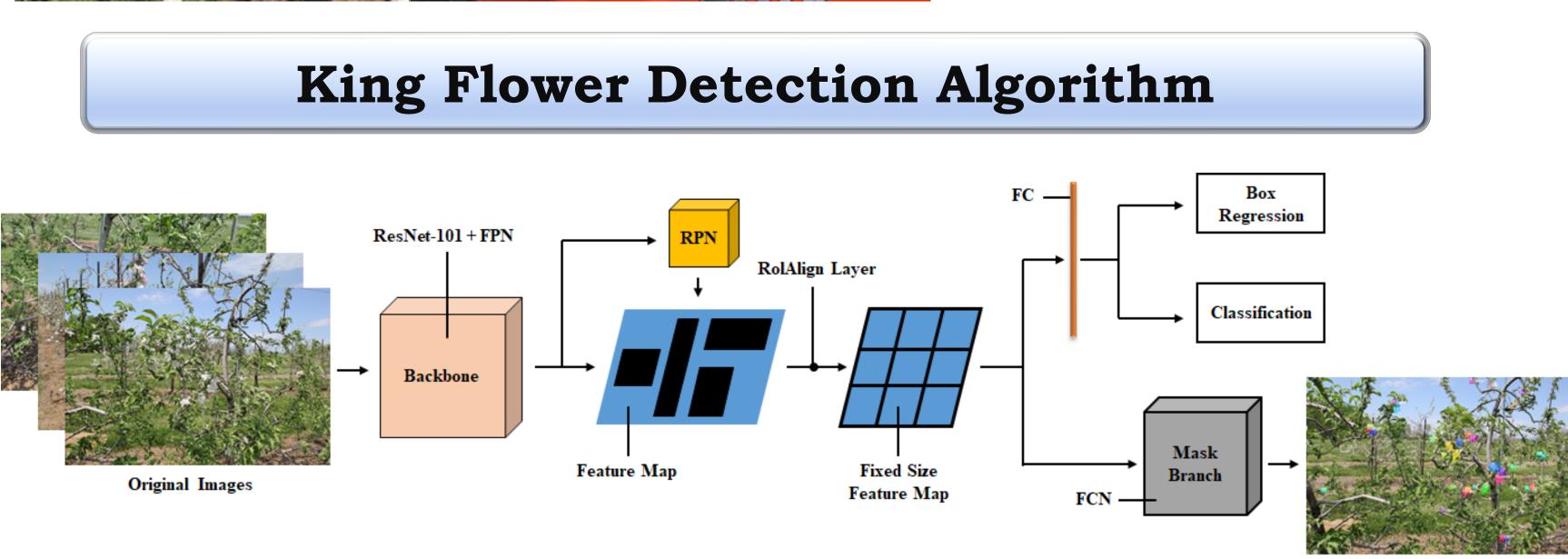


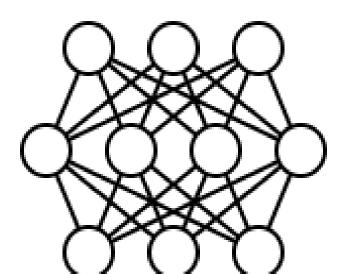
Introduction: Precision Apple Pollination

- Supplies of pollination services (honeybees) do not match the increasing demands.
- Robotic pollination system provides promising solution.
- An autonomous robotic pollination system consists of a vision system, a manipulator, and an end effector.
- A vision system that can accurately locate king flowérs is necessary.
- The success of this study will improve the efficiency of pollination and reduce labor cost.

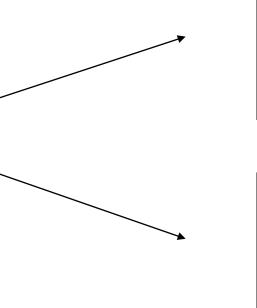


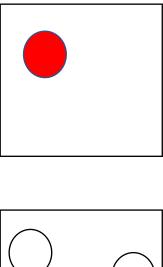


Mask R-CNN based instance segmentation (state-of-art) Transfer learning using COCO dataset



Mask R-CNN + Instance Segmentation





Flower

Mask R-CNN Based King Flowers Identification for Precision Apple Pollination

Xinyang Mu, Long He Department of Agricultural and Biological Engineering, Pennsylvania State University, University Park, PA



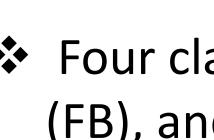
Image Acquisition System

✤ Materials:

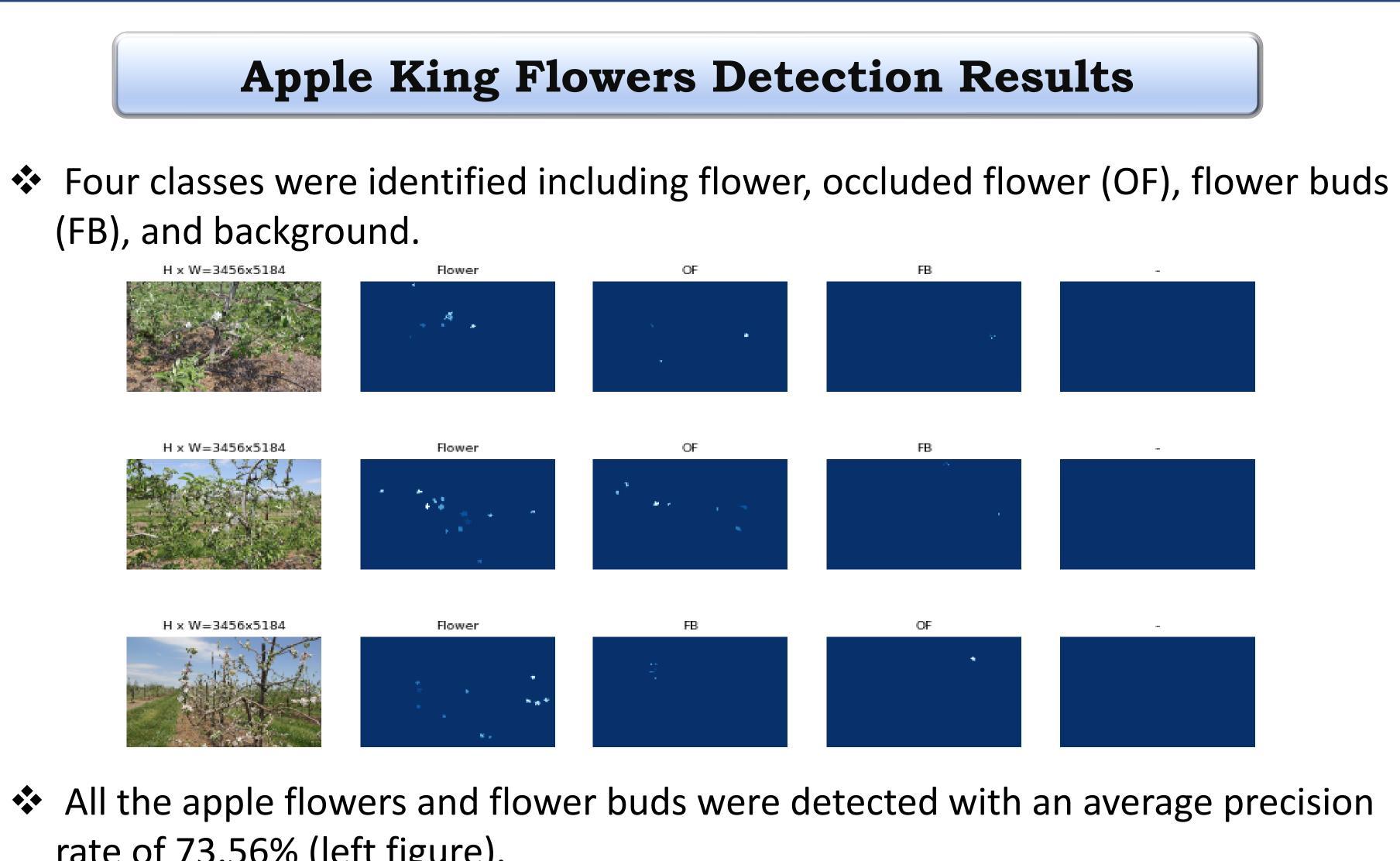
- ZED2 camera
- Kubota utility vehicle
- Aluminum frame
- Cultivars: Gala / Honeycrisp
- 800 images were collected

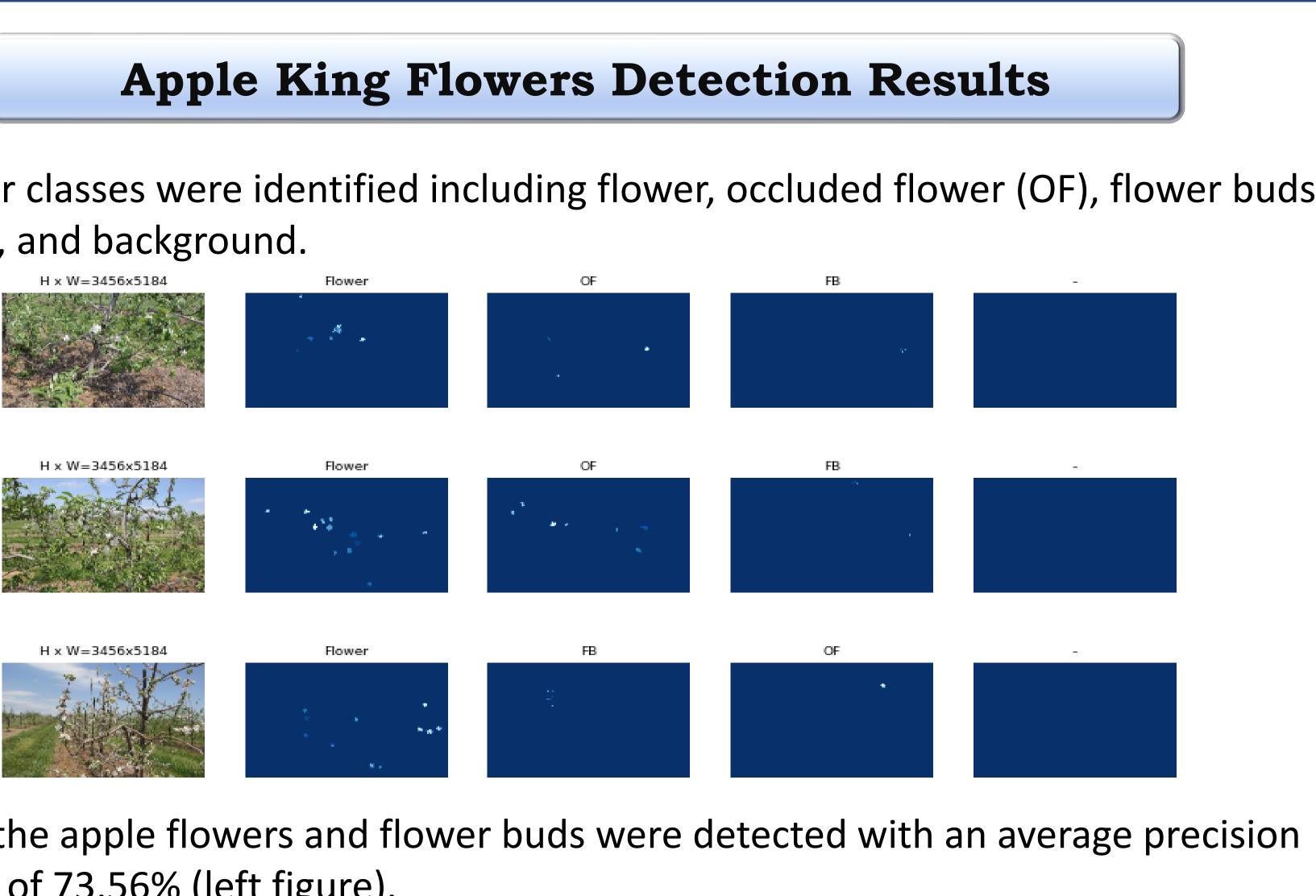
Output Images with Masks













| Date | Counted flowering stages (ground truth) | Detected flower stages (algorithm) | Accuracy of king flower detection (%) | Date | Counted flowering stages (ground truth) | Detected flower stages (algorithm) | Accuracy of king flower detection (%) |
|-----------|--|--|--|-----------|--|--|--|
| 4/15/2021 | 5% | 4.6% | 92% | 4/15/2021 | 0% | 0% | 100% |
| 4/16/2021 | 10% | 8.5% | 85% | 4/16/2021 | 3% | 2.7% | 90% |
| 4/17/2021 | 20% | 16.6% | 83% | 4/17/2021 | 13% | 11.4% | 88% |
| 4/18/2021 | 30% | 23.7% | 79% | 4/18/2021 | 20% | 16.8% | 84% |
| 4/19/2021 | 40% | 29.6% | 74% | 4/19/2021 | 50% | 39.5% | 79% |
| 4/20/2021 | 75% | 46.5% | 62% | 4/20/2021 | 75% | 56.3% | 75% |
| 4/21/2021 | 100% | 60% | 60% | 4/21/2021 | 100% | 69% | 69% |
| | | | | | | | |

Acknowledgement: This research was supported in part by United States Department of Agriculture (USDA)'s National Institute of Food and Agriculture (NIFA) Federal Appropriations under Project PEN04653 and Accession No. 1016510, Northeast Sustainable Agriculture Research and Education (SARE) Graduate Student Grant GNE22-293, and a USDA-AMS Specialty Crop Multi-State Grant Program (Award No. K3055). We also would like to give our special thanks to Dr. James Schupp for the ground truth information.

Decision Making for King

rate of 73.56% (left figure).

The king flowers within each cluster were selected using image processing algorithm (right figure).

Comparison between flower detection results and manually counting. The accuracy of king flower detection kept decreasing as the development of flowering stage.

Multiple factors: occlusion by other objects / orientation of king flowers

Conclusion

A novel approach for apple king flowers detection was developed using Mask R-CNN based instance segmentation.

The detection target focused directly on the king flowers, which are the most critical blossoms to perform precision pollination

